

International Journal of Mechanical Engineering and Robotics Research

CONTENTS

Volume 14, Number 3, 2025

Implementation of Surface Response Optimization in the Design of Adaptive Lightweight Gripper	229
<i>Mohammad Al Mashagbeh*, Saleh K. Elayyan, and Migdad Tamimi</i>	
Optimal Multi-stepped Sonotrode Design for Ultrasonic Plastic Welding	238
<i>A. D. Younis, Ziad. S. Al Sarraf, Abdulhaqq A. Hamid*, and Zaid T. ALdabbagh</i>	
Thermal Analysis of the MRB during Downhill Braking	245
<i>Hoang Quang Tuan, Vu Hai Quan, and Trinh Minh Hoang*</i>	
Characteristics of Side Force and Fluid Flow Separation Past Vertical Stabilizer and Rudder of Microlight Aircraft Model	252
<i>Nasaruddin Salam, Rustan Tarakka, Lukman Kasim*, Muhammad Agung, and Hamsa</i>	
Implementing Predictive Analytics to Optimize Parameter for Automation Vertical Farming Using Deep Learning.....	262
<i>Sasithorn Chookaew and Suppachai Howimanporn*</i>	
Van and Truck Classifications of 3D LiDAR Perception for Autonomous Vehicle Navigation	276
<i>Ericsson Yong, Muhammad Aizzat Zakaria*, Mohamad Heerwan Peeie, and M. Izhar Ishak</i>	
Modeling of Cyborg-Cockroach Swarm Using Agent-Based Simulation.....	282
<i>Le Minh Triet and Nguyen Truong Thinh*</i>	
Feedback Control Using ARMA to Maneuver Wheelchairs	299
<i>Chadi F. Riman* and Wael H. F. Aly*</i>	
Design and Analysis of Efficient Desert Straw Checkerboard Laying Machine Based on PLC Automatic Control Technology.....	309
<i>Qingshan Wu, Mianhao Zhu*, Yanqi Shang, Yue Chen, Huibao Zhang, and Zhimin Sun</i>	
Neural-Backstepping Adaptive Control for Nonlinear Motion of Sliding Mobile Robots	323
<i>Vo Thu Hà* and Thân Thị Thương</i>	
In Silico Evaluation of Temperature and Geometrical Parameters on Material Extrusion 3D Printing.....	340
<i>Sidonie F. Costa*, Fernando M. Duarte, and José A. Covas</i>	
Safe Reinforcement Learning Using Sequential Constraints for Collision Avoidance	347
<i>Gyuyong Hwang and Gyuho Eoh*</i>	
Development and Implementation of Autonomous Mobile Robots for Warehouse Applications	360
<i>Tri Cuong Do and Tri Dung Dang*</i>	
Design and Simulation of a Foot Prosthetic Testing Machine Compliant with ISO 10328 Standard	367
<i>Ndaru Adyono, Ahmad Khairul Faizin, M. Danny Pratama Lamura, and Wahyu Dwi Lestari*</i>	