

# International Journal of Mechanical Engineering and Robotics Research

## CONTENTS

---

---

### Volume 5, Number 3, July 2016

#### Materials Science

Effects of Surface Modification on Improvement of Diamond Coating on Tungsten Carbide Cutting Tool..... 168  
*Chii-Ruey Lin, Minh-Khoa Bendao, and Chi-Wen Liou*

Morphological Studies on Europium Selenide Thin Films.....172  
*G. D. Bagde, C. T. Londhe, and K. N. Shivalkar*

Characterization, Analysis and Modeling of a MEMS Based Nitinolactuator ..... 176  
*Alkausil Tamboli and A. Vimala Juliet*

#### The Design and Development Technology of Robot

Design and Implementation of a Path Finding Robot Using Flood Fill Algorithm..... 180  
*Semuil Tjiharjadi and Erwin Setiawan*

Fuzzy Logic PID Based Control Design for a Small Underwater Robot with Minimum Energy Consumption  
..... 186  
*Ali Jebelli and Mustapha C. E. Yagoub*

3D Map Building Using Mobile Robot with Scan Device ..... 191  
*Shohei Kita Jae Hoon Lee and Shingo Okamoto*

Development of a Biped Walking Robot with Antagonistic Actuation ..... 196  
*Takashige Yano, Jae Hoon Lee, and Shingo Okamoto*

#### Aerospace Engineering and Electronic Technology

Calculation of Turn Radius and Bank Angle at Different Altitudes Based on RNP AR.....202  
*Ozlem Sahin*

Energy and Exergy (ENEX) Analyses of a MD-80 Aircraft.....206  
*Onder Turan*

#### Mechanical Engineering and Application

Technology of WAVE and Feature Cutter Volume of Manufacturing .....210  
*Liu Jialiang, Chen Zhuoning, Xu Tongming, and Zhang Fen*

Ergonomics Design Procedure for Female Urination Device in Computer System.....217  
*Lijing Wang and Xueli He*

Influence of Module and Pressure Angle on Contact Stresses in Spur Gears .....224  
*M. V. Murali and S. L Ajit Prasad*

Heat Transfer Analysis of Fins with Spine Geometry Using Differential Transform Method .....	229
<i>Melih Fidanoglu, Guven Komurgoz, and Ibrahim Ozkol</i>	
A System and Method of Maneuvering Powered Exoskeleton Using Mechanical and Hydraulic Feedback ....	234
<i>M. K. Vimal Govind, K. Padmakumar, and E. B. Sreejith Babu</i>	